



TITLE: Armuno™ Desktop Robotic Arm

REV 0.4

BY: Microbotlabs

ATTRIBUTION: Derivative Work Based On: LICENSE: MeArm V0.4 - Pocket Sized Robot Arm by phenoptix **CC BY-SA 3.0**

MODIFICATIONS:

Added plain bearing to base servo to dampen oscillations.
Widened, tapered and added additional bracing to arm structural links for increased rigidity. Added servo motor cable management slots and cutouts.

Lowered base box frame servo mount locations to lower the CG slightly.

Added holes to base plate to allow mounting arm to heavier base to prevent

Reactionary movements of the arm assembly. Added geometry for optional thin plain bearings at linkage pin points.

Armuno and Logo Design is a trademark of Microbotlabs